

## Sensor board broadcast frame

Revision	Date	history
rev. a	20/08/15	Starting revision
rev. b	01/03/2015	Added pressure ( 0xB. )

### General description

Sensor board built for the Visible Things will broadcast the sensor information based on an internal ( design choice ) timer.

The broadcast frame is of type “ADV\_NONCONN\_IND”, ( PDU type 0010 ) which has a limited payload of 28 bytes.

To make the payload flexible, the payload is built using “fields”, one field to identify a specific sensor type.

### Field format

Each field is built by a sequence of bytes.

The first byte will identify the field type ( 4 MSB ) and the field scale factor ( 4 LSB )

The following bytes ( up to 3 bytes ) will give the value for the field, the basic units of measurement will be multiplied by  $2^{(\text{scale\_factor} - 8)}$  to get the effective value of the measurement, and will apply for all the following measurements.

This is the list of available field

Field name	Filed ID ( MSB )	Parameter byte 1	Parameter byte 2	Parameter byte 2
reserved	“0000”			
Acceleration	“0001”	X-value, 2's complement value in units of 0.01g	Y-value, 2's complement value in units of 0.01g	Z-value, 2's complement value in units of 0.01g
Gyroscope	“0010”	X-value 2' complement value in units od 0.01deg/s	Y-value 2' complement value in units od 0.01deg/s	Z-value 2' complement value in units od 0.01deg/s
Magnetic field	“0011”	X-value 2' complement value in units of $10^{-6}T$	Y-value 2' complement value in units of $10^{-6}T$	Z-value 2' complement value in units of $10^{-6}T$
Light	“0100”	Ambient light units ok klux	Infrared light units of mW/cm <sup>2</sup>	UV light units of mW/cm <sup>2</sup>
Temperature	“0101”	Ambient temperature unit of Celsius		
Noise	“0110”	Noise level		

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		units of dB ( referred to the stadrad audio scale, 0dB = 20μPa )		
Battery voltage	“0111”	Battery voltage, units of 0,01V		
RF signal level from the sensor radio ( RSSI )	“1000”	Signale level fro the radio, in units of dBm		
Cap. sens	“1001”	X-cap ccoordinate 0-100% in units of 1%	Y-cap ccoordinate 0-100% in units of 1%	
Humidity	“1010”	Humidity in %, scale 100%, unit 1%		
Pressure	“1011”	Pressure is in mBar		
TDB	“1100”			
TDB	“1101”			
TDB	“1110”			
TDB	“1111”			

## Payload format

Payload is simply a sequence of fields; **the application MUST scan the payload to find the fields and identify their values. The detailed content can change during the development of the Visible Things demo.**

The Freescale KL26Z Freedom board has FXOS8700CQ and an ( un-calibrated ) ambient light sensor, and a capacitive slide sensor

*The payload build of 17 bytes*

0x18, X-acc, Y-acc, Z-acc, 0x38, X-mag, Y-mag, Z-mag, 0x48, Ambient, 0x00, 0x00, 0x98, Slide, 0x00, 0x78, battery voltage.

*The Silabs sensor demo has many different sensors, and almost fill up the payload ( 26 bytes )*

0x18, X-acc, Y-acc, Z-acc, 0x38, X-mag, Y-mag, Z-mag, 0x28, X-rot, Y-rot, Z-rot, 0x48, Ambient, proximity, UV, 0xA8, Humidity ( SI7021 ), 0x58, temperature ( SI7021 ), 0x68, noise ( ICS43432 ), 0x78, battery voltage, 0x88, RSSI

*The Cypress sensor demo has many different sensors, with this payload ( 14 bytes )*

0x18, X-acc, Y-acc, Z-acc, 0x48, Ambient, proximity, UV, 0xA8, Humidity ( SI7021 ), 0x58, temperature ( SI7021 ), 0xB8, pressure